

Dust Distribution during Reionization

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Abstract.

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1. Introduction

The importance of the Cosmic Microwave Background (CMB) as a cosmological tool has been demonstrated thoroughly during the last few years. It has been used to evaluate the age of the universe, the Hubble parameter, the baryon content, the flatness and the optical depth, Bennett et al. (2003); the non-Gaussianity of the primary fluctuations, Komatsu et al. (2003); the Sunyaev-Zeldovich fluctuations from the first stars, Oh et al. (2003); the primordial magnetic fields, Subramanian et al. (2003); the spatial curvature of the universe, Efstathiou (2003); the formation of population III stars, Cen (2003); the neutrino masses, Hannestad (2003) and many other phenomena.

However, in order to interpret the CMB signal correctly, its foreground must also be well known.

In this paper we focus on one particular aspect of the foreground of the CMB, the primordial dust. This dust was created during the reionization period in the first generation of stars and then ejected into the interstellar medium (ISM). The dust will therefore partly block the path of the CMB photons, and slightly deform the spectrum. As we have shown in an earlier paper Elfgren & Désert (2004), this dust will have a characteristic spectrum proportional to a primary anisotropy (ΔT) spectrum times the frequency squared. The dust spectrum was shown to be lower than the CMB by roughly two orders of magnitude because the heating from the stars is significantly less than that of the CMB at the time.

Nevertheless, the dust will also have a characteristic spatial distribution which could be used to identify its signal. The objective of this paper is to determine this distribution and its impact on different measurements of the CMB. Of particular interest is the Planck mission, but also other instruments, like ... could be interesting. The spatial distribution is estimated from the GalICS N -body simulations of dark matter which are described in more detail in section 2. The dust distribution is

then combined with the intensity of the dust emission as calculated in Elfgren & Désert (2004), and this is integrated along the line of sight. The resulting power spectrum is then plotted in terms of the spherical harmonics C_l and compared to detection limits of Planck.

In our model, we assume a Λ CDM universe with $\Omega_{tot} = \Omega_m + \Omega_\Lambda = 1$, where $\Omega_m = \Omega_b + \Omega_{DM} = 0.133/h^2$, $\Omega_b = 0.0226/h^2$ and $h = 0.72$ as advocated by WMAP, Spergel et al. (2003), using WMAP data in combination with large scale structure observations (2dFGRS + Lyman α).

2. Dark Matter Simulations

The distribution of dark matter in the universe was calculated using the GalICS (Galaxies In Cosmological Simulations) program. The cosmological N -body simulation we refer to throughout this paper was done using the parallel tree-code developed by Ninin (1999). The power spectrum was set in agreement with Eke et al. (1996): $\sigma_8 = 0.88$, and the Dark Matter (DM) density field was calculated from $z=35.59$ to $z=0$, outputting 100 snapshots spaced logarithmically in the expansion factor.

GalICS is a hybrid model for hierarchical galaxy formation studies, combining the outputs of large cosmological N -body simulations with simple, semi-analytic recipes to describe the fate of the baryons within dark matter haloes. The simulations produce a detailed merging tree for the dark matter haloes, including complete knowledge of the statistical properties arising from the gravitational forces.

The basic principle of the simulations is to randomly distribute a number of dark matter particles N^3 with mass M_{DM} in a box of size L^3 . Then, as time passes, the particles interact gravitationally, clumping together and forming structures. The clumps of Dark Matter are called halos and in our simulation we require at least 5 particles to clump together before we call it a halo. There are supposed to be no other forces present than

the gravitation and the boundary conditions are assumed to be periodic.

In the simulations we used, the side of the box of the simulation is $L = 100h^{-1}$ Mpc and the number of particles are 256^3 which implies a particle mass of $\sim 5.51 \times 10^9 h^{-1} M_{\odot}$. Furthermore, the cosmological parameters were $\Omega_{\Lambda} = 2/3$, $\Omega_m = 1/3$ and $h = 2/3$. Between the assumed initial dust formation at $z \sim 15$ and the end of this epoch in the universe at $z \sim 5$, there are 51 snapshots. In each snapshot a friend-of-friend algorithm was used to identify virialized groups of at least five DM particles. The number of particles have been set low in order to produce halos already at $z = 14.7$.

In order to make a correct large-scale prediction of the distribution of the Dark Matter and therefore the dust, the size of the box would have to be of Hubble size, i.e. 3000 Mpc. However, increasing the size of the box and maintaining the same number of particles would mean that we loose in mass resolution, which is not acceptable if we want to reproduce a fairly realistic scenario of the evolution of the universe.

There is another way to achieve the desired size of the simulation without loosing in detail or making huge simulations. This method is called MoMaF (Mock Map Facility) and is described in detail in Blaizot et al. (2003). The basic principle is to use the same box, but at different stages in time and thus a cone of the line of sight can be established. In order to avoid replication effects, the periodic box is randomly rotated for each timestep. This means that there will be loss of correlation information on the edges of the box, since those parts will be gravitationally disconnected from the adjacent box. Fortunately, this loss will only be of the order of 10% as shown in Blaizot et al. (2003).

2.1. Validity of Simulation

The distribution of galaxies resulting from this GalICS simulation has been compared with the 2dS Colless et al. (2001) and the Sloan Digital Sky Survey Szapudi et al. (2001) and found to be realistic on the angular scales of $3' \lesssim \theta \lesssim 30'$, see Blaizot et al. (2003). The discrepancy in the spatial correlation function for other values of θ can be explained by the limits of the numerical simulation. Obviously, any information on scales larger than the size of the box is not reliable. *More volume effects discussion?* Since the simulation gives reasonable predictions of the matter distributions today, it seems likely that it is also valid at higher z when the early dust is produced.

3. Model

Since very little is known about the actual distribution of the dust throughout the universe at this time, we simply assume that the dust distribution follows the dark matter distribution. We propose two different ways for this to happen and explore these. The first is to let the dust be proportional to the dark matter halos, the second is to make a hydrodynamical smoothing of the dark matter density field and set the dust density proportional to this density:

$$\rho_{dust}(\mathbf{r}, z) \propto \rho_{DM}(\mathbf{r}, z), \quad (1)$$

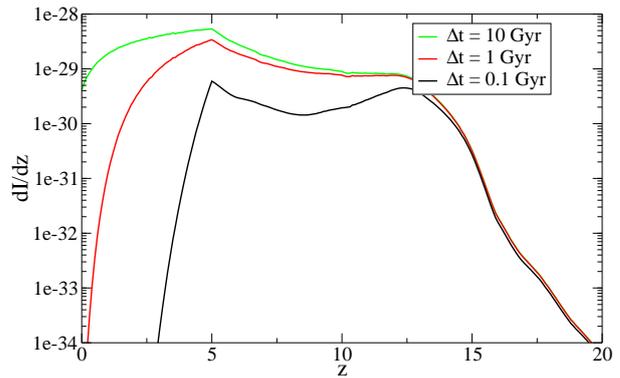


Fig. 1. Intensity contribution from the dust per timestep z . *Add CMB?*

where ρ_{DM} represents either the Halo method or the Particle method.

In order to estimate the measured intensity, we need to do this distribution in terms of this intensity instead. In our previous paper, Elfgren & Désert (2004), we calculated the intensity as a function of redshift, supposing that none of the light emitted from the stars is absorbed. This is close enough to the truth since there are more than 100 ionizing photons produced per baryon. The result is plotted in Fig. 1.

In our present model, the dust intensity is spatially distributed such that

$$\frac{dI}{dz}(\mathbf{r}, z) \propto \rho_{DM}(\mathbf{r}, z). \quad (2)$$

The MoMaF method (section 2) is then used to project the emitted intensity from the dust on a $45' \times 45'$ patch along the line of sight. Within each box equation 2 is normalized to produce $\int_{\text{box depth}} dI/dz(z)$ when averaged over the projected box. If a box is deeper than the time-step is long, the box is simply chopped there. For $z < 2.3$, the time-step is too short but this is of little consequence since the dust density is so low at this time. The box is divided into a grid according to the resolution that we wish to test. For Planck this means a grid that is 9×9 pixels, for Scuba 45×45 .

To check the resulting intensity image, I've calculated its $\sum dI_{xy}/N_{pix}^2$ and found it to be equal to $\int dI(z)dz$ to within a few per cent.

Figure of Cl with only DM?

4. Results and Discussion

As described above, the MoMaF technique produces an image of the line of sight. This image represents the patch of the sky covered by the box, 150 co-moving Mpc^2 which translates to $\sim 45'$ and is apodized (smoothed on the edges), so as to avoid artefacts on the edges. Thereafter the image is Fourier transformed into frequency space P_k . In order to convert this spectrum into spherical harmonics correlation function we apply the following transformation:

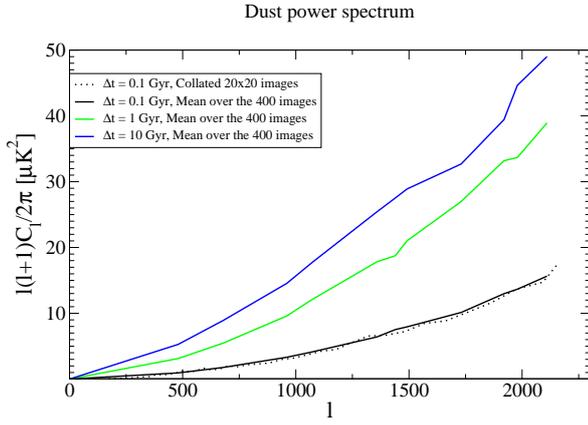


Fig. 2. Dust power spectrum for a map $45' \times 45'$ and Planck resolution $5'$ for three different lifetimes for the dust particles, 0.1, 1, 10 Gyrs. The last line ...

$$l = k \cdot (2\pi) / (4 \cdot \sin(\theta/4)) \cdot N_{map} / N_{fft} \quad (3)$$

$$C_l = \theta^2 C_k. \quad (4)$$

These C_l is then calculated in units of $[\mu\text{K}^2/B_\nu(T_{CMB})]$ at a frequency $\nu = 353$ GHz (one of the Planck detectors work at this frequency). As discovered in Elfgren & Désert (2004), the intensity is proportional to the frequency squared which means that the power spectrum at a frequency ν will be

$$C_l(\nu) = C_l(353 \text{ GHz}) \cdot \left(\frac{\nu}{353 \text{ GHz}} \right)^4. \quad (5)$$

In order to estimate an average power spectrum, 400 such images were generated and the C_l were averaged of these. For comparison, we also tried to paste all these images together and calculate the C_l for this (180×180 pixels) image. The result was very similar to the average C_l . The resulting power spectra can be seen in 2. As described in Elfgren & Désert (2004), the lifetime of these dust particles is a largely unknown factor and we plot three different lifetimes, 0.1, 1, 10 Gyrs. Furthermore, the intensity is proportional to the fraction of the formed metals that actually end up as dust, which we assumed to be $f_d = 0.3$. This means that the intensity $C_l(f_d) = C_l(f_d = 0.3) \cdot f_d^2$.

The dust frequency spectrum will be distinctly different from that of other sources in the same frequency range. As shown in Elfgren & Désert (2004), it will be $\propto \nu^2$. We compare this spectrum with that of the CMB $\Delta T/T$ and that of galactic dust, $T=17$ K, Boulanger et al. (1996). In order to focus on the forms of the spectra, we normalize the three curves to one at $\nu = 353$ GHz. The result is presented in Fig. 3. In case of a weak dust signal, this frequency signature could allow us to distinguish the dust signal from the CMB and other foregrounds.

4.1. Detection with Planck?

The Planck satellite, due for launch in 2007, will have an angular resolution of $\sim 5'$ and will cover the whole sky. Our simulated box of $45'^2$ will thus correspond to 9×9 pixels in Planck.

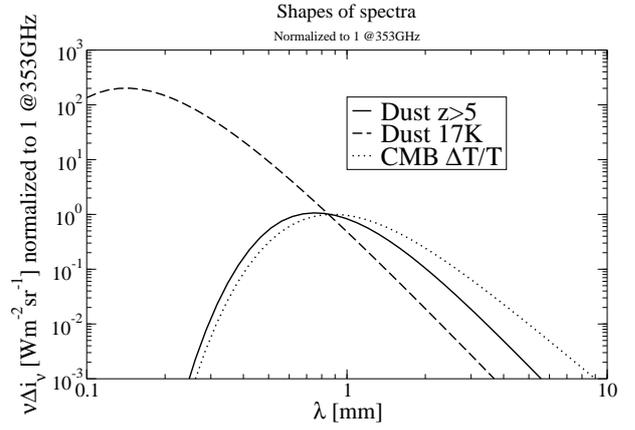


Fig. 3. The form of the early dust spectrum compared to the form of galactic dust (with a temperature of 17K) and the CMB. The curves have been normalized to 1 at 353 GHz.

Frequency [GHz]	100	143	217	353	545	857
$FWHM$ [$^\circ$]	9.5	7.1	5.0	5.0	5.0	5.0
s_X [$\mu\text{Ks}^{1/2}$]	32.0	21.0	32.3	99.0	990	45125

Correlations on larger angular scales than $45'$ will not be available from our simulations. However, the dust correlations will increase at smaller angles while the CMB and many other signals will decrease. This means that our lack of information on angular scales $\ell \lesssim 250$ will not be of any consequence, as can be seen in Fig. 4. Planck will measure the CMB at $\nu = 100, 143, 217, 353, 545,$ and 857 GHz. We have chosen $\nu = 353$ as our reference frequency. At higher frequencies, the galactic dust will become more of a nuisance and at lower frequencies the CMB primary anisotropies will tend to dominate. To transpose to other frequencies, recall from Eq. 5, that $C_l \propto \nu^4$.

In order to test to detectability of the dust with Planck, we evaluate the total error

$$E = \sqrt{\frac{2}{(2\ell + 1)f_{cut}L}} \times (E_{CMB} + E_{instrument}) \quad (6)$$

$f_{cut} = 0.8$ is the percentage of the sky used, L is the bin-size, E_{CMB} is the cosmic variance and the instrument error is

$$E_{instrument} = f_{sky} \frac{4\pi s_X^2}{t_{obs}} \cdot e^{\ell^2 \cdot \sigma_b^2} \cdot \frac{\ell(\ell + 1)}{2\pi}, \quad (7)$$

where $f_{sky} = 1$ is the percentage of the sky covered, s_X is the noise per second [$\mu\text{Ks}^{1/2}$], $t_{obs} = 14 \cdot 30 \cdot 24 \cdot 3600$ is the observation time (14 months), and $\sigma_b = FWHM/2.35$ is the lobe sensitivity in radians ($FWHM = \text{Full Width Height Median}$).

For Planck, the values of these parameters are given in table 4.1. The values of the cosmic variance E_{CMB} was taken from the Λ -website: <http://lambda.gsfc.nasa.gov/>.

The resulting error for a binning of $L = 500$ along with the dust power spectrum is plotted in figures 4-8. In figure 4, the frequency $\nu = 353$ GHz is fixed while ℓ is varied. We note that $\ell \sim 1000$ seems to be a good place to search for dust. At low ℓ , the error due to the cosmic variance dominates, at high ℓ the instrument noise.

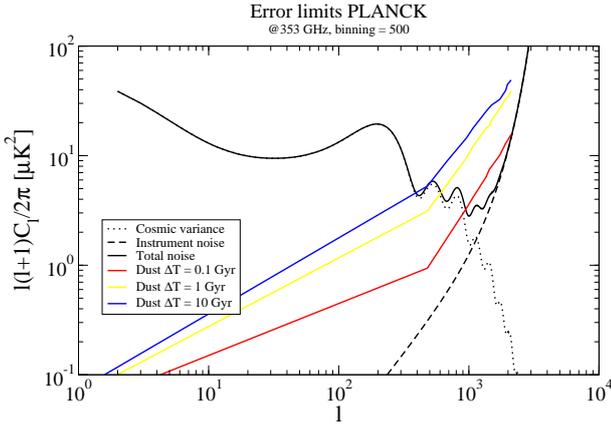


Fig. 4. Error limits at 353 GHz.

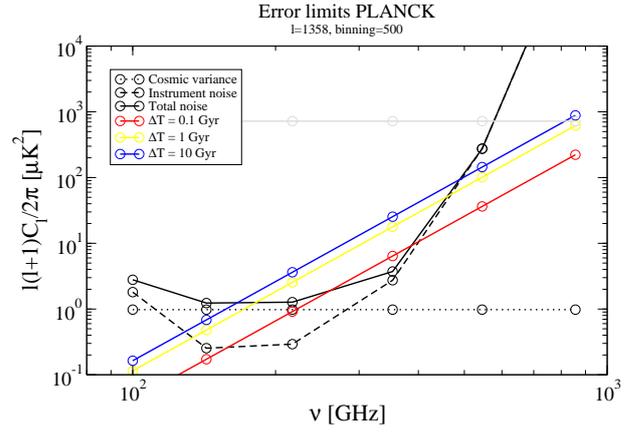


Fig. 6. Error limits at $l=1358$.

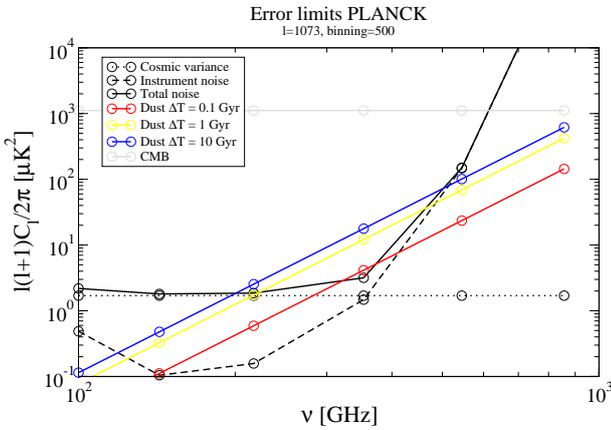


Fig. 5. Error limits at $l=1073$.

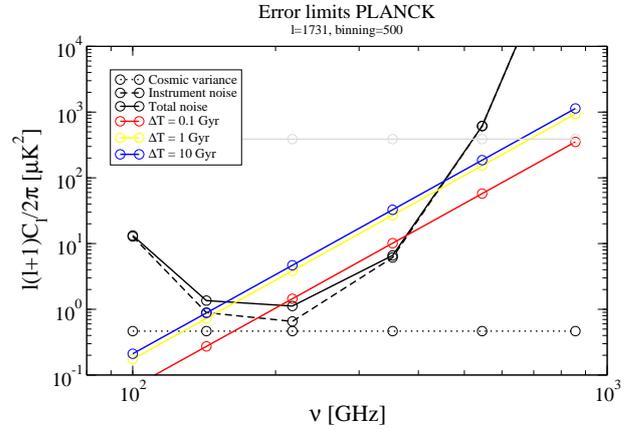


Fig. 7. Error limits at $l=1731$.

In figures 5 – 8, the binning center is fixed while the Planck frequencies constitute the variable. The fourth point in the figures correspond to $\nu = 353$ GHz and apparently gives the best signal over error ratio. At low frequencies the cosmic variance is important, at high frequencies, the instrument error.

4.2. Detection with Scuba?

4.3. Discussion

Correlations/competition with other effects that are present in structures

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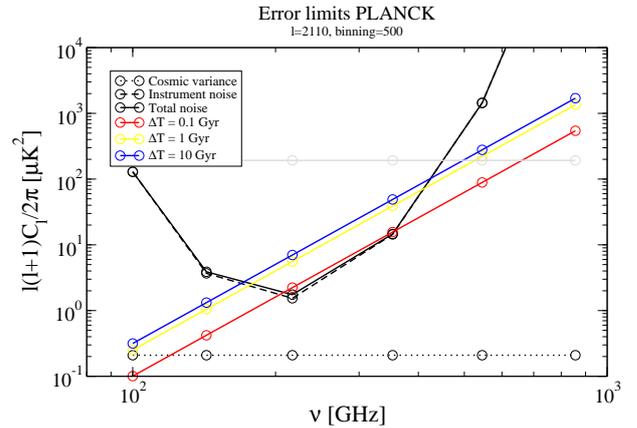


Fig. 8. Error limits at $l=2110$.

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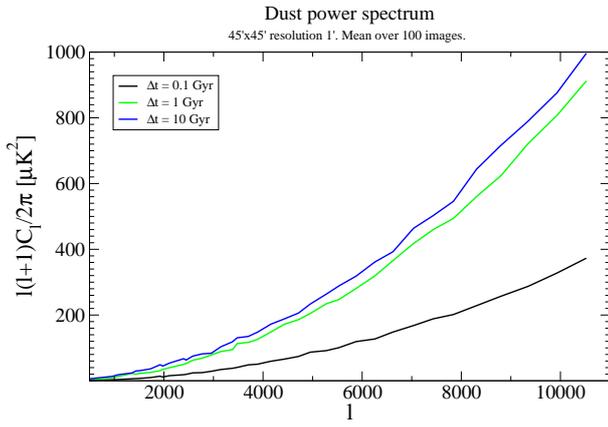


Fig. 9. Dust power spectrum for a map $45' \times 45'$ and Scuba resolution $1'$.

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